



User Guide – Evaluation Kit

WLG-75-R range motor with embedded encoder

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ABOUT US

Tekceleo is a forward-thinking technology company dedicated to innovation and the creation of cutting-edge solutions. With a commitment to excellence, we specialize in providing innovative solutions with advanced motion and aerosol generation technologies.

Our mission is to simplify and empower lives across various industries, including medical, pharma, aerospace, and industrial automation. Tekceleo's diverse team of experts collaborates to drive technological advancements and deliver results that exceed expectations. We're not just a company, we're a catalyst for progress, and we invite you to join us on this exciting journey.

KEY FACTS



**2 Patent
Families**



**A unique
Know-How**



**75% of Sales
Abroad**



Conditions of Use

General Characteristics and Warnings

1. General Characteristics

- To operate continuously, the motor needs to dissipate heat. It is advisable to mount it on a metal cooling plate.
- Performances are ensured as long as the temperature of the motor remains under 45 degrees.
- We highly recommend to use a flexible coupling between the WLG-75 motor and the load in order to ensure performances.
- The controller can be shared through license agreement for customers who want to incorporate the electronics into their own systems.
- All our controller can directly control continuous movement with switches.
- Software can be shared and/or customized on demand.

2. Warnings

- For precise motion control it is necessary to use a microcontroller connected to the controller. In our evaluation kit we offer specific STM32 microcontroller with embedded demo software for easily handle our motors.
- The motor shaft must absolutely not be loaded by radial load more than specified : 60 N.
- The motor must be mounted on cooling plate designed in order to better dissipate the heat emanating from the motor.
- Optimal size is aluminum plate with the specified dimensions : 100 x 150 x 8 mm.
- Make sure to screw the motor using the right screw length (M4x0,7 – 6 mm deep MAX in the motor).
- Please respect the recommended tightening torque for M4 screws : 3,5 Nm.

WLG-75-R – Kit Presentation

Evaluation kit for Tekcelele's Wavelling Technology

The purpose of this kit is for you to easily use, test, evaluate and implement Tekcelele's unique ultrasonic motors.

To understand more about our technology you can consult our website :

www.tekcelele.com

Tekcelele's team is here to help you moving forward in your use case, for information, this kit intended use is for :

- **Directly use** our technology, as this kit is a standalone system that can be already used.
- **Evaluate** our technology, in order to ensure its viability for your project
- **Prototype** : all the parts of this kit are modular and can be implemented in a prototype
- **Be integrated** directly in your device.



Kit Presentation – Presentation of Parts

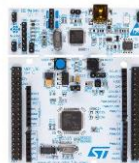
Content and included parts of this kit



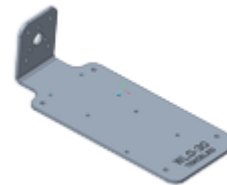
WLG-75-R



WLG-75 ECU



**STM32
MICROCONTROLLER**



**HEAT DISSIPATION
PLATE**



24V POWER SUPPLY



**CABLE ECU-MOTOR
(30cm)**

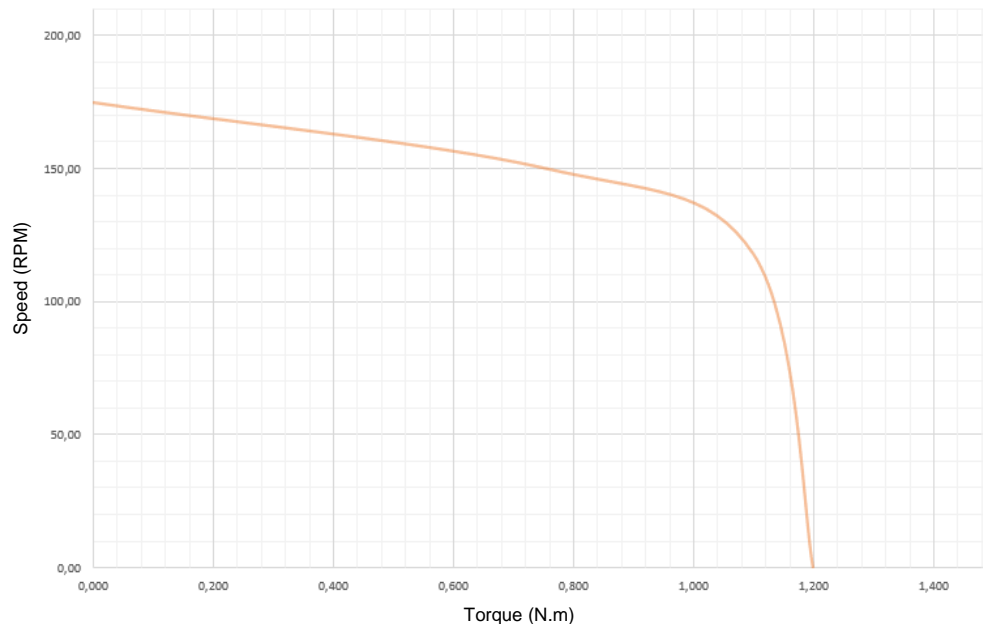


**FREE DEMO
SOFTWARE**

Technical Specifications

WLG-75-R Datasheet

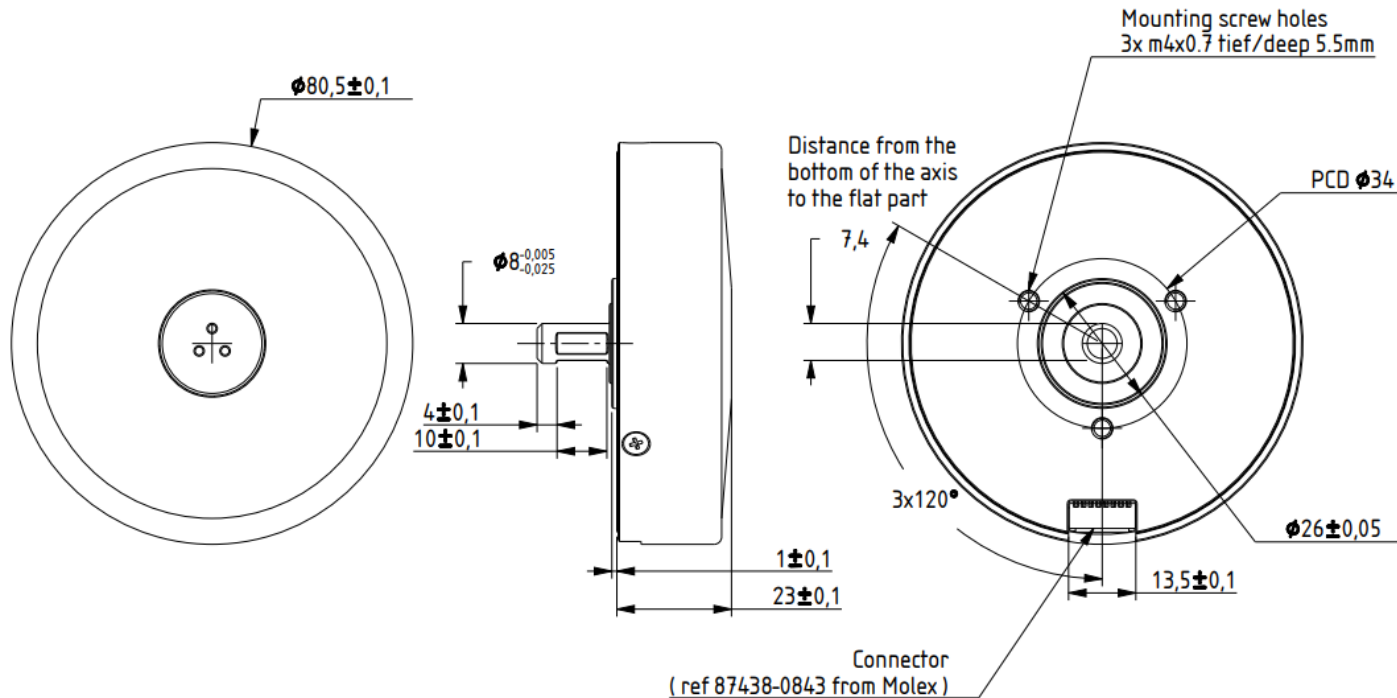
MOTOR DATA WITH EMBEDDED ENCODER	VALUES
Max No load speed	175 RPM
Stall torque	1,2 N.m
Rated speed at maximum output	150 RPM
Rated torque at maximum output	0,75 N.m
Holding torque	1,5 N.m
Maximum power	12 W
Operating temperature	0°C to 45°C
MECHANICAL DATA	VALUES
Max radial load, 5mm from flange	10 N
Max axial load dynamics	10 N
Max force for press fits (static, shaft supported)	120 N
Shaft concentricity	± 0,04 mm
Weight	282 g
ELECTRICAL DATA	VALUES
Maximal power consumption	24 VDC / 2,9A
Recommended power supply	24 VDC / 4A
NON-MAGNETIC VERSION	YES



PRECISION	VALUES
Built-in encoder	Yes, optical with quadrature output
Max Encoder Resolution	0,0156° / 273 μr
Possible Max encoder Resolution (custom)	0,0039° / 68 μr

Technical Datasheet

WLG-75-R Dimensions



Technical Datasheet

WLG-75-R Board dimensions

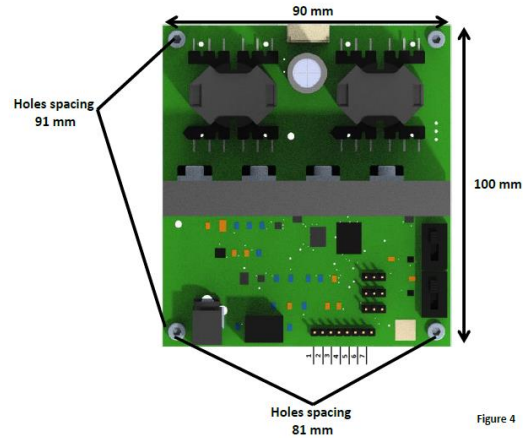
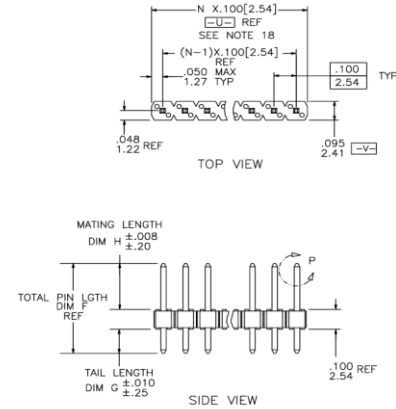
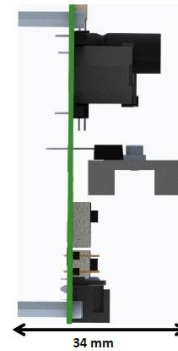


Figure 4

BOARD DIMENSIONS



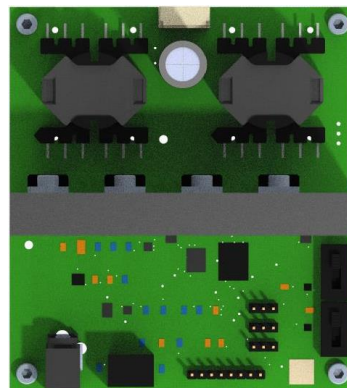
PINS DIMENSIONS

Mounting recommendations

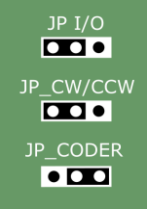
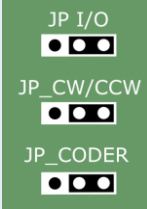
Instruction to set-up and start the WLG-75 motor

- **Power up** : Connect the power supply into an electrical outlet.
- **Motor control** :
 - In order to turn on / turn off the motor, activate the on/off Switch.
 - To change the direction of the rotation, activate the **CW/CCW Switch**.
- **Speed control** : In order to control the speed and turn on the motor, connect the ground pin 2 and the speed pin 1 to a voltage generator. If the speed pin is not connected, the motor will not rotate.
- **Jumper settings** :
 - In order to control the motor via the manual switches, place the jumpers in the Switch Control position.
 - In order to control the motor via pin 3 and 4, place the jumpers in the External Control on pins 3 and 4 position.

PIN	INPUT / OUTPUT	SPECIFICATIONS
1	I	Speed control using analog voltage 0 – 3,3 VDC
2	-	Ground
3	I	On Off digital control TTL level signal (0 or 5 VDC)
4	I	CW / CCW digital control TTL level signal (0 or 5 VDC)
5	O	Incremental encoder signal A (5760 increments per rotation)
6	O	Incremental encoder signal B (5760 increments per rotation)
7	O	Incremental encoder index
8	-	Not used



1 2 3 4 5 6 7 8

JUMPER CONFIGURATION	
Switch control	External control
	

Mounting recommendations

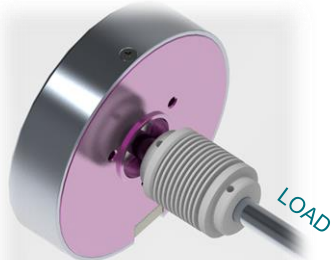
Instruction to set-up and start the WLG-75 motor



The motor shaft must absolutely not be loaded by radial load more than specified : 60 N



The motor must be mounted on cooling plate designed in order to better dissipate the heat emanating from the motor.



We highly recommend to use a flexible coupling between the WLG-75 motor and the load in order to ensure performances. Please find on the table the main characteristics to respect.

Our ref : A2533 from A.C.C.&S.

COUPLING CHARACTERISTICS	VALUES
Axial stiffness	11,2 N/mm
Radial Stiffness	38,1 N/mm
Inertial torque	1,61x10 ⁻⁶ kg.m ²



We recommend to fix the piezoelectric motor on a metal plate to dissipate the heat generated by the motor. Optimal size is aluminum plate with the specified dimensions : 100 x 150 x 8 mm

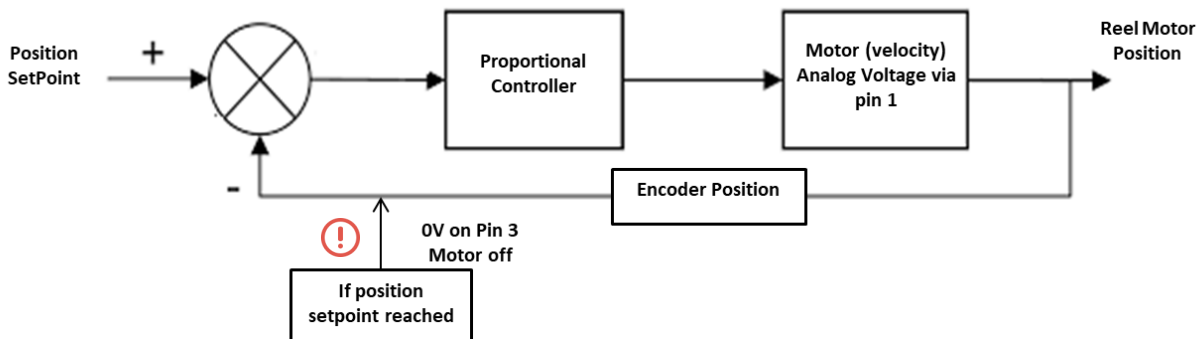
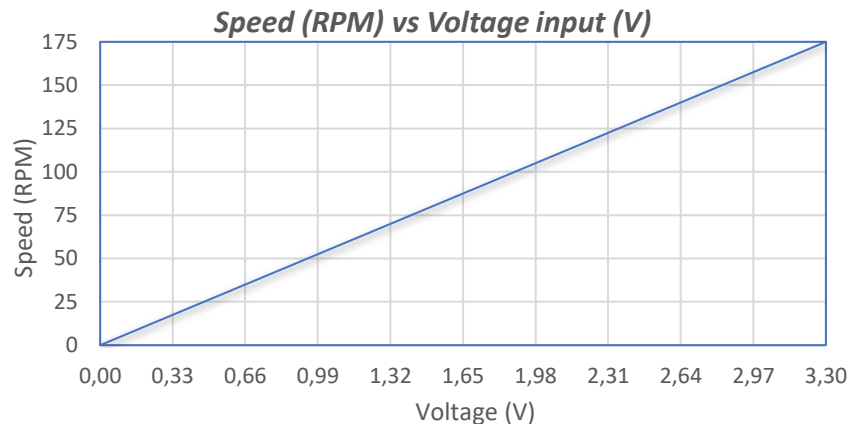


Make sure to screw the motor using the right screw length (M4x0,7 – 6 mm deep MAX in the motor). Please respect the recommended tightening torque for M4 screws : 3,5 Nm

Control specifications

Instruction to control the WLG-75 motor

CHARACTERISTICS	VALUES
On / Off response time (Pin 3)	< 500 μ s
Speed change response time	< 50 ms
Closed loop position controller (see figure below)	P control proportional
<u>In case you need to control the position of the motor :</u> In order to take advantage of the on / off response time of the motor, it is preferable to send a 0V on pin 3 once the motor has reached its position (see figure below)	
ENCODER DATA	VALUES
Two channel quadrature digital outputs for direction sensing : A and B	5760 increments per revolution each
One channel, Index digital output I (Z)	1 increment per revolution



Evaluation Kit – Technical Support

Tekceleo's offer a complete technical support

- Directly contact your salesperson for any question. You can also directly contact Tekceleo using the contact@tekceleo.fr email address.
- In case of any trouble or issue you can freely open a support ticket by following this process :
 - Send an email to support-mot-1@tekceleo2.odoo.com
 - Object : order number + name of company
 - Content : explain the problem you're experiencing and join as many data, picture or video that you can to help us troubleshoot your problem.
- Tekceleo's team will get back to you as soon as possible to troubleshoot and resolve your problem.

At any point of your project you can contact Tekceleo's for help regarding uses, integration or development project. We can also offer customization and engineering services if needed.

CONTACT US



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